

$$\begin{aligned}
 & \frac{DV}{Dt} \uparrow \\
 & F = ma \leftarrow \\
 & F_f = \mu F_N \\
 & \frac{F_f}{F_N} = \mu \rightarrow \frac{m(17.5501)}{mg} = \mu = 1.79 \\
 & F = ma \leftarrow \\
 & F_g = mg
 \end{aligned}$$

$$\frac{DV}{Dt} = \frac{V_f - V_i}{t_f - t_i} = \frac{0 - 26.817}{1.52802} = -17.5501 \frac{m}{s^2}$$

$$v_f^2 = v_i^2 + 2ad$$

$$0 = v_i^2 + 2ad$$

$$\frac{-v_i^2}{2d} = a$$

$$\frac{mg}{mg} = \mu$$

$$\frac{\cancel{m} \left(\frac{-v_i^2}{2d} \right)}{\cancel{m}g} = \mu$$

$$\frac{-v_i^2}{2dg} = \mu$$

$$\frac{F_f}{F_N} = \mu$$

Forces

Force = push or pull

Contact

Spring
Friction
Push
Tension

Non-Contact

gravity
Electromagnetic
Strong/weak
nuclear

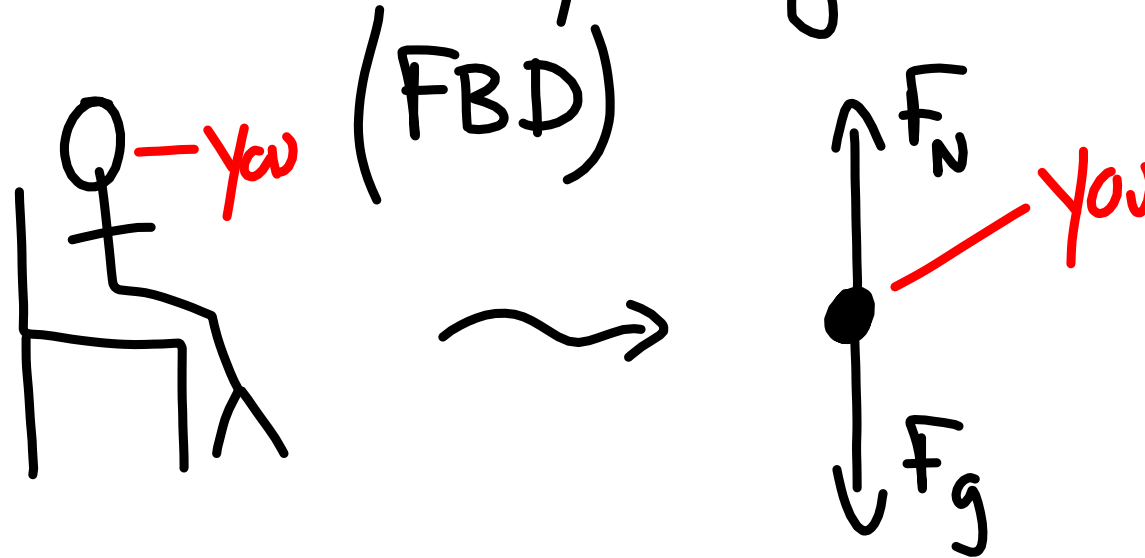
<u>Force</u>	<u>Relative Strength</u>	<u>Range</u>
Strong	1	$\sim 10^{-15} \text{ m}$
Electromagnetic	10^{-2}	∞
Weak	10^{-6}	$\sim 10^{-18} \text{ m}$
gravity	10^{-39}	∞

Remember: $F = ma$

or: $\frac{F}{a} = m$

↓
Constant of
Proportionality

Free Body Diagrams



or: $\sum \vec{F} = ma$

Summation